

Let's Agree to Agree: Targeting Consensus for Incomplete Preferences through Majority Dynamics

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1. Introduction



Deciding for an Online Platform



Deciding for an Online Platform



We have never used Bridge
AppEar is better than C-nnect

a b
↓
 c

a b
↓
 c

Deciding for an Online Platform



We have never used Bridge
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Bridge is more stable than AppEar

a b
↓
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a b
↓
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b c
↓
 a

b c
↓
 a

Deciding for an Online Platform



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↓
 c

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b c
↓
 a

b a c

Deciding for an Online Platform



The committee meets to discuss the alternatives and starts by comparing AppEar and Bridge

a b
↓
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a b
↓
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b c
↓
 a

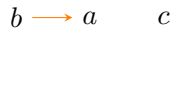
b c
↓
 a

b a c

Deciding for an Online Platform



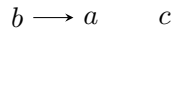
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Deciding for an Online Platform



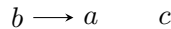
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Deciding for an Online Platform



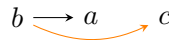
The merits of Bridge over C-nnect are then discussed



Deciding for an Online Platform



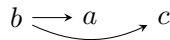
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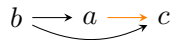
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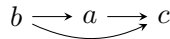
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Deciding for an Online Platform



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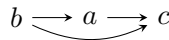


↳ Note the existence of an obvious consensual alternative now: Bridge.

Deciding for an Online Platform



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Our goal is to study this dynamical process!

The Majority Dynamic

Let $\sigma = (p_1, \dots, p_\ell)$ be an *update order* over ordered pairs of alternatives.

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$$\succsim_i^t \parallel \begin{cases} \succsim_i^{t-1} & \text{if } ab \text{ or } ba \in \succsim_i^{t-1}: \text{ no update if the pair is already ranked} \\ \llbracket \succsim_i^{t-1} \cup \{ab\} \rrbracket & \text{if } N_{ab} > N_{ba}: \text{ a preferred to b if the majority prefers a over b} \end{cases}$$

$\llbracket \succsim \rrbracket$ denotes the *transitive closure* of the order \succsim .

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How does the majority dynamic affect consensus?

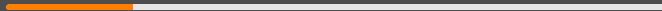
How does the majority dynamic affect consensus?

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graph TD; A[How does the majority dynamic affect consensus?] --> B[What is consensus?]; A --> C[What kind of effects?]
```

What is consensus?

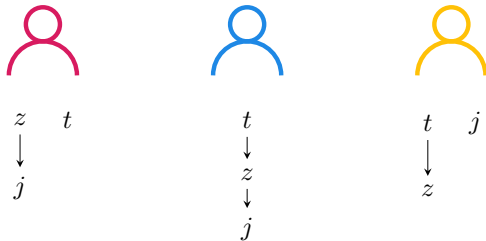
What kind of effects?

2. Condorcet Consensus

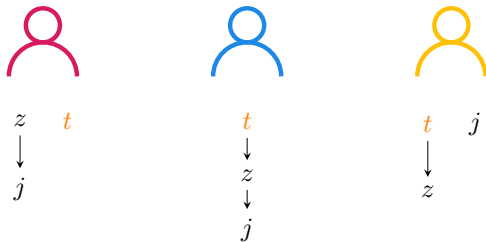


Condorcet Consensus: There exists an alternative *strictly* winning all pairwise majority contests against other alternatives.

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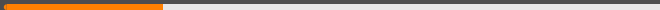


t against z : 2 for t 0 for z

t against j : 1 for t 0 for j

Condorcet Consensus

└ Preservation



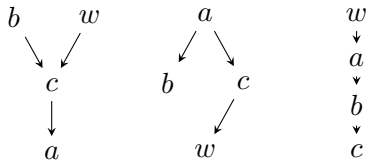
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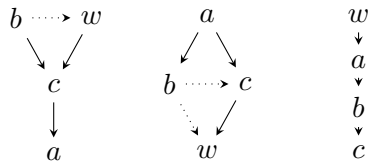


w is the Condorcet winner

Preserving Condorcet Consensus

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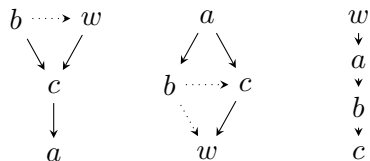
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Updating on bc and bw

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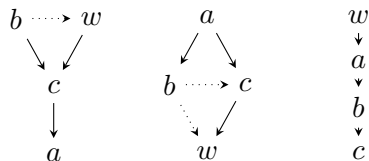
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No Condorcet winner

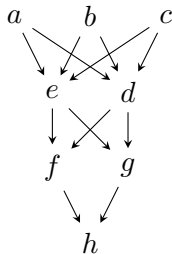
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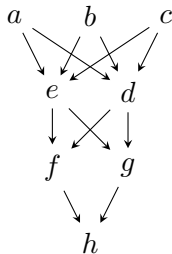


For 3 alternatives and less: Majority dynamic preserves existence of but not identity.

Strict Weak Orders: alternatives ranked in different levels, incomparabilities within levels



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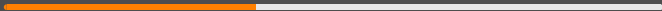
- If i already has a comparison between a and w , nothing changes ✓
- If we update on wa or aw then i will prefer w over a since w is a Condorcet winner ✓
- If we update on another pair leading to $a \succ_i^t w$. Then:

$$a \longrightarrow b \longrightarrow c \cdots z \longrightarrow w$$

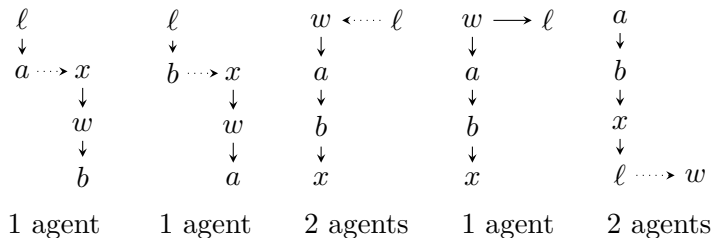
This is impossible with strict weak preferences if i does not have opinion on a and w . ✓

Condorcet Consensus

└ Quality



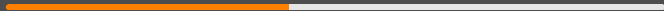
A Condorcet loser can be turned into a Condorcet winner.



➡ Condorcet consensus is preserved (w initially and ℓ eventually) but the consensual alternative at the end used to be a Condorcet loser.

Condorcet Consensus

└ Controlling



So far we focused on preserving consensus, i.e., universal guarantees that the majority dynamic does not harm consensus.

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What's next? Exploring what the decision maker can achieve by selecting a specific update order.

Positive and Negative Control

Positive Control: The majority dynamics enables positive control if for all profile *with* initial consensus, there exists an update order preserving the consensus.

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- there exists an update order preserving the *absence* consensus; or,
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↳ The decision maker can control the update order to prevent consensus from happening.

Positive Control: The majority dynamics *enables* positive Condorcet consensus control.

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↳ For a profile with a as initial Condorcet consensus, update according to $ab, ac, ad, ae \dots$

Negatively Controlling Condorcet Consensus

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↳ Consider a profile without Condorcet consensus. For any a , there is b such that if we first update on ba , a cannot become a Condorcet winner.

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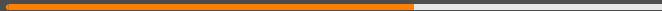
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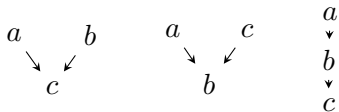
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 - If there are no Condorcet winner at the end, we are done ✓
 - If $x \neq w$ is a Condorcet winner at the end, we have two update orders leading to two different Condorcet winners ✓

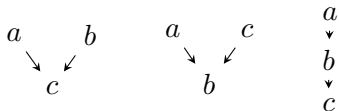
3. Other Consensus Notions



Unanimity Undominated

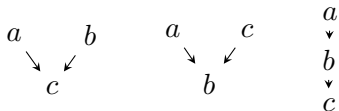


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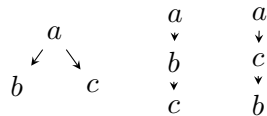


Consensus requires *unicity*

Unanimity Undominated

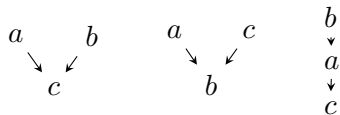


Unanimity Dominant

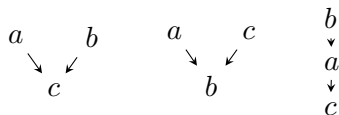


Consensus requires *unicity*

Majority Undominated

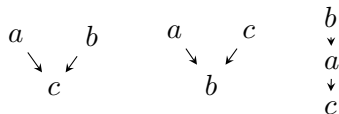


Majority Undominated



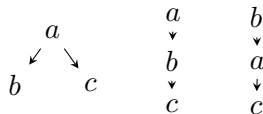
Majority should be *strict*
Consensus requires *unicity*

Majority Undominated



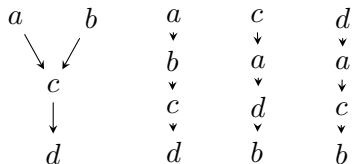
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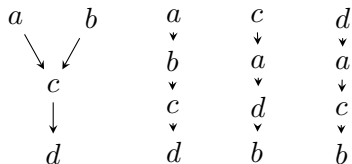
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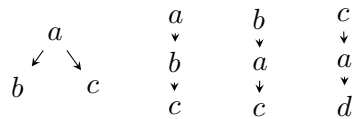
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Consensus requires *unicity*

	Preserving consensus	Positive control	Negative control
Condorcet	✗ (✓)	✓	✓

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Condorcet	✗ (✓)	✓	✓
Plurality Undominated	✗	✗	✗

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Condorcet	✗ (✓)	✓	✓
Plurality Undominated	✗	✗	✗
Plurality Dominant	✗	✗	✗

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Plurality Undominated	✗	✗	✗
Plurality Dominant	✗	✗	✗
Majority Undominated	✗	✓	✗

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Plurality Undominated	✗	✗	✗
Plurality Dominant	✗	✗	✗
Majority Undominated	✗	✓	✗
Majority Dominant	✓	✓	✗

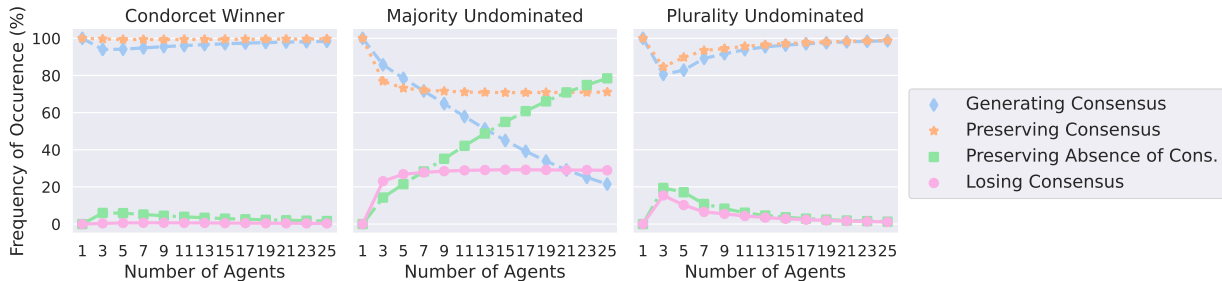
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Unanimity Undominated	✗ (✓)	✓	✓

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Majority Undominated	✗	✓	✗
Majority Dominant	✓	✓	✗
Unanimity Undominated	✗ (✓)	✓	✓
Unanimity Dominant	✓	✓	✗

4. Experimental Analysis

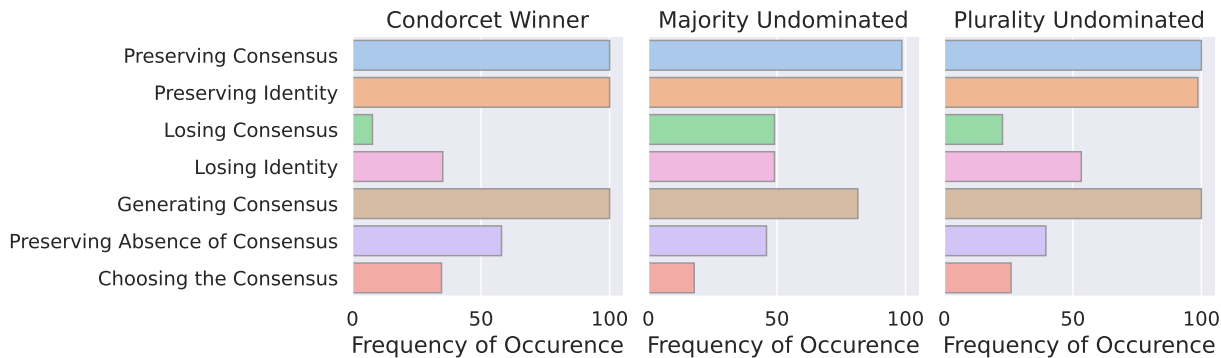


Quantifying the Effects on Consensus



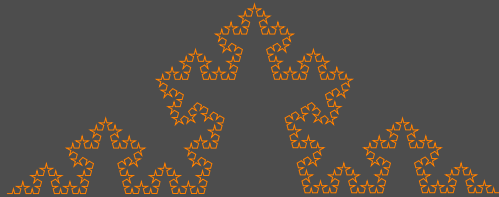
- Numbers of agents varying in 1, 3, 5, ..., 25
- 5 000 000 random profiles each time (uniform distribution over $a \succ b$, $b \succ a$ and $a \sim b$, repeat until transitive)

Quantifying the Opportunities for Control



- 11 agents and 4 alternatives
- 20 000 random profiles
- All of the 46 080 possible update orders on each profile

5. Conclusion



What have we done? Studied the majority dynamic and the effects it can have on consensus for several consensus notions.

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What is still to be done? Several ideas:

- Computational complexity of control problems (selecting the update order to achieve some goal)
- Computational complexity of good update orders (minimising number of updates, etc...)
- Guarantees about distance to consensus when it is not achieved
- And so many others...



Sirin



Simon



Zoi

Do you still have questions?